

ERRATUM

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Erratum to: Kinematical and static force analysis on redundant drive wire mechanism with velocity constraint modules to reduce the number of actuators

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**Erratum to: *Robomech J* (2016) 3:22
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Unfortunately, the original version of this article [1] contained an error. The acknowledgements section was included incorrectly. The correct acknowledgements section can be found below.

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Reference

1. Le TN, Dobashi H, Nagai K (2016) Kinematical and static force analysis on redundant drive wire mechanism with velocity constraint modules to reduce the number of actuators. *ROBOMECH J* 3:22. doi:[10.1186/s40648-016-0057-z](https://doi.org/10.1186/s40648-016-0057-z)

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