## ERRATUM





Erratum to: Kinematical and static force analysis on redundant drive wire mechanism with velocity constraint modules to reduce the number of actuators

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## Erratum to: Robomech J (2016) 3:22 DOI 10.1186/s40648-016-0057-z

Unfortunately, the original version of this article [1] contained an error. The acknowledgements section was included incorrectly. The correct acknowledgements section can be found below.

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The online version of the original article can be found under doi:10.1186/s40648-016-0057-z.

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## Reference

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